Errata

Robust Control of Nonlinear Systems Using Model-Error Control Synthesis

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EQUATION (45) should be corrected as follows:
Equation (45) should read

$$\bar{u} = -\frac{1}{\hat{c}_6}(\hat{c}_1 + \hat{c}_2\hat{\phi} + \hat{c}_3\hat{p} + \hat{c}_4|\hat{\phi}|\hat{p} + \hat{c}_5|\hat{p}|\hat{p})$$

$$+ \frac{1}{\hat{c}_6}\left\{\ddot{r} - \vartheta(\hat{p} - \dot{r}) - \eta\,\text{sat}\left[\frac{(\hat{p} - \dot{r}) + \vartheta(\hat{\phi} - r)}{\rho}\right]\right\}$$

Classification of Out-of-Plane Swing-By Trajectories

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FIGURES 2, 3, 7, and 8 have an error in the legend of the axes. For each of these figures, the horizontal axis should represent the angle β and the vertical axis should represent the angle α. The reader should also note that there are corresponding errors in the text.